

Official Sumobots Rule Book

By

MTRNSoc



Changelog:

Date	Version number	Changes	
25/03/2023	1.0	Initial release	
11/05/2023	1.1	Advanced rules and arena specs	
10/06/2023	1.2	Advanced rules around servos	
18/06/2023	1.3.0	Updated Ring specifications;	
		including obstacles for the advanced	
		stream. (NULL as of ver. 1.5)	
18/06/2023	1.3.1	Blanket ban on magnets.	
29/02/2024	1.4	Added description of boss battles	
22/06/2024	1.5	Updated Ring picture and specs.	
		Changed max. time for each round	
		Changed mode for Advanced Stream.	
		Redifined the definition of a 'win'	
		Added 'Sumobots Game Modes'	

Contents

Ch	angelog	:	i	
Co	ntents		. ii	
1	Overview of the Sumo Match			
	1.1.1	Overview of Sumobots	. 1	
	1.1.2	Overview of Sumo Matches	. 1	
	1.1.3	Carrying Sumo Matches	. 1	
	1.1.4	Definition of a Win	. 1	
	1.1.5	Violations and Penalties	. 2	
	1.1.6	Injuries and Accidents during the Match	. 2	
2	Requirements for Robots		. 2	
	2.1.1	Robot Specifications	. 3	
	2.1.2	Standard Stream Restrictions	. 3	
	2.1.3	Advanced Stream Restrictions	ii 1 1 1 2 2 3 3 3 4 4 4	
	2.1.4	General Robot Restrictions	. 3	
3	Sumo	Sumo Ring Specifications		
4 SumoBot Game Modes		Bot Game Modes	. 4	
	4.1.1	Boss Battles	. 4	
Re	ferences		. 6	
An	pendix:		6	

1 Overview of the Sumo Match

1.1.1 Overview of Sumobots

Two robots compete in a head-to-head match following the basic system of traditional human sumo matches. The sole purpose is a pushing match between the two robots to force the other from the arena. Robots are allowed no weapons (no sharp objects, no powered flipping, no projectiles, no sticky substances).

1.1.2 Overview of Sumo Matches

A match is fought between two teams, each team having one or more contestants. Only one team member may approach the ring; other team members must watch from the audience. The match starts at the judge's command and continues until a contestant wins two rounds. The judge determines the winner of the match.

After all competitors have finished their battles and the winner is determined, there will be a free for all Boss Battle. All competitors are welcome to test their Sumobots against Bossbots provided by either the Committee members or the UNSW Makerspaces. (see "Boss Battles")

1.1.3 Carrying Sumo Matches

- 1. Each match will have 3 rounds
- 2. Rounds will last a maximum of 2 minutes
- 3. Once the round start has been announced, robots shall wait 5 seconds before moving
- 4. The team who wins two rounds first shall win the match.
- 5. The judges will decide the winner of each round, and the winner of the match.
- 6. When a round is not won by either team within the time limit, an extended round may be fought during which the team who wins the round will win the match.
- 7. If an extended round match continues longer than 2 minutes without a winner, the judges will decide the match's outcome.
- 8. The placement of robots at the start of the match are set on opposing sides. See "Sumo Ring Specifications" for details on bot placements.

1.1.4 Definition of a Win

- 1. A round has been won by a team when:
 - a. A team legally forces the body of the opposing robot off the ring.
 - b. The opposing robot has fallen outside the ring on its own.
 - c. Either of the above takes place at the same time the match ends.
- 2. When a wheeled robot has fallen over while still on the ring or in similar conditions, a win will not be counted, and the match continues.
- 3. When judges' decision is called for to decide the winner, the following points will be taken into considerations:
 - a. Technical merits in movement and operation of a robot
 - b. Minor violations during the match (see "Violations and Penalties")
 - c. Attitude of the players during the match
- 4. The match shall be stopped, and a rematch started under the following conditions:

- a. The robots are entangled or orbiting each other with no perceivable progress for five seconds. If it is unclear whether progress is being made or not, the judge can extend the time limit for observable progress for up to 30 seconds.
- b. Both robots move, without making progress, or stop (at the exact same time) and stay stopped for five seconds without touching each other. However, if one robot stops its movement first, after five seconds it will be declared as not having the will to fight. In this case the opponent shall be declared the winner, even if the opponent also stops. If both robots are moving and it isn't clear if progress is being made or not, the judge can extend the time limit up to 30 seconds.
- c. If both robots fall off the ring at about the same time, and it cannot be determined which fell first, a rematch is called.

1.1.5 Violations and Penalties

A team will be declared in violation of the rules if:

- 1. Their robot does not meet the specifications detailed in "Requirements for Robots" below.
- 2. A player utters insulting words to the opponent or to the judges or puts voice devices in a robot to utter insulting words or writes insulting words on the body of a robot or performs any insulting action.

Teams declared in violation of the rules shall lose the match and be ordered to leave.

A minor violation will be declared if a player:

- 1. Enter the ring during the match, except when the player does so to take the robot out of the ring upon the judge's announcement of stopping the match. To enter the ring means:
 - a. A part of the player's body is in the ring, or
 - b. A player puts any mechanical kits into the ring to support his/her body.
- 2. Performs the following deeds:
 - a. Demand to stop the match without appropriate reasons.
 - b. Take more than 30 seconds before starting the next round or rematch, unless the judge announces a time extension.
 - c. Start operating the robot within five seconds after the chief judge announces the start of the match
 - d. Does or says that which disgraces the fairness of the match.

If a minor violation is declared twice in one match, a round win point will be given to the opposing team.

1.1.6 Injuries and Accidents during the Match

- 3. A player can request the match to stop when he/she is injured, or his/her robot had an accident, and the game cannot continue.
- 4. When the match cannot continue due to a player's injury or robot's accident, the player who is the cause of such injury or accident loses the match. When it is not clear which team is such a cause, the player who cannot continue the game, or who requests to stop the game, shall be declared as the loser.
- 5. Whether the match should continue in case of injury or accident shall be decided by the judges and the Committee members. The decision process shall take no longer than five minutes.

2 Requirements for Robots

2.1.1 Robot Specifications

Robots competing in the Standard and Advanced streams must have dimensions, weight and budget less than or equal to that specified in Table 1 below.

Table 1: Robot Specifications

	Height	Width	Length	Weight	Budget
Standard	Unlimited	200mm	200mm	1kg	\$100*
Advanced	Unlimited	250mm	250mm	1.5kg	\$100*

^{*}Does not include cost of kits

2.1.2 Standard Stream Restrictions

Robots competing in the Standard competition:

- 1. Must use components only from the supplied kit and preapproved extras list. This list will be updated as the competition runs (so feel free to ask about adding something to this list) but will not be changed after week 4. It includes:
 - a. Up to 3 extra IR sensors
 - b. Up to 3 extra Ultrasonic Sensors
 - c. Any additional non-powered wheels
 - d. Anything purely cosmetic (e.g. LEDs)
- 2. Must not make modifications to the drivetrain.
- 3. Extra non-powered wheels are allowed

2.1.3 Advanced Stream Restrictions

Robots competing in the Advanced competition:

- 1. Must use the supplied motors, wheels and battery to drive the robot, and may not use any additional motors in the robot's drive system.
- 2. May use additional components not included in the supplied kit
- 3. May make modifications to the drivetrain.
- 4. May use up to 2 external servos that do not contribute to drive system (no other motors may be used externally)
- 5. Servos cannot actively harm opposition
- 6. Description of use for servos must be submitted to organizers before Week 8 Monday
 - a. Email: mechatronics.unsw@gmail.com
 - b. Please Include Team Name and a photo of the Sumobots

2.1.4 General Robot Restrictions

The following rules apply to all robots competing in Sumobots, including both Standard and Advanced streams.

- 1. Robots must be autonomous and not remotely controlled.
- 2. Robots must not intentionally damage opponent robots. Normal pushes and bangs are not considered intent to damage. Do not use parts that are dangerous.
- 3. Jamming devices, such as IR LEDs intended to saturate the opponents IR sensors, are not allowed.
- 4. Parts that could break or damage the ring are not allowed.
- 5. Devices that can store liquid, powder, gas or other substances for throwing at the opponent are not allowed.
- 6. Flaming devices are not allowed.

- 7. Devices that throw things at your opponent are not allowed.
- 8. Sticky substances to improve traction are not allowed. Driven wheels/tires in contact with the ring must come from the Sumobots kit.
- 9. Devices to increase down force, such as a vacuum pump or magnets, are not allowed.
- 10. All edges, including the front scoop, must not be sharp enough to scratch or damage the ring, other robots, or players. In general, edges with a radius of greater than .005", as would be obtained with an unsharpened .010" thick metal strip, should be ok. Judges or competition officials may require edges that they deem too sharp to be covered with a piece of tape.
- 11. Magnets are not allowed.
- 12. Any other concerns should be taken up with mentors and organisers.

3 Sumo Ring Specifications

The ring used for matches will be the same for standard and advanced streams. Its specifications include:

- 1. The ring is circular, with 120cm outer diameter and 115cm inner diameter (black playing surface with 2.5cm thick white border line)
- 2. The ring is made of 18mm thick MDF, painted with spray paint.
- 3. Four different starting positions to choose from (see Figure 1). Each team must decide prior to the match and inform the judge. Teams cannot change their mind after confirming the position until the next round.
- 4. There should also be a space of suitable size outside the ring which must be void of objects and players, so that bots do not pick up false sensor data.

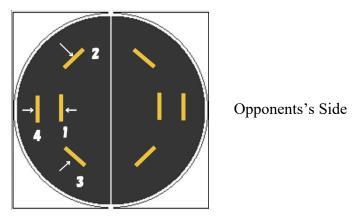


Figure 1: Top View of Sumo Ring.

Arrow indicates the direction that the main ultrasonic sensor OR ramp faces

4 Sumobot Game Modes

4.1.1 Boss Battles

Following the normal match rules, teams may choose to compete against Bossbots, provided by the MTRNSoc subcommittee and the UNSW Makerspaces. The game mode presents itself as a tiered battle where teams can advance from tier to tier to gain rewards for each battle won.

The Bossbots follow the same rules as the advanced stream but breaks ONE particular rule. This rule could be weight, dimension, sensors or budget. They cannot, however, add mechanics that may damage competing bots. The Bossbots are created to pose a challenge to players but cannot be impossible to beat.

References

There are no sources in the current document.

Appendix: